# **Rotary Position Technology**



# Magnetic rings RI20/LI20









High rotational speed

High IP

Shock/vibration resistant

Reverse polarity protection

#### **Robust**

- · Increased ability to withstand vibrations and rough installation. Eliminates machine downtime and repairs. High shock and vibration resistance, thanks to non-contact technology.
- · Stays sealed even when subjected to harsh everyday use. Offers security against failures in the field. Potted housing with up to IP67 protection.

#### Compact

· Installation depth only 16 mm, width of magnetic ring 10 mm



• Large hollow shaft up to 30 mm Can be used even where space is very tight

### Simple installation

- Fast start-up of the measuring system Easy fixing of the magnetic ring and the sensor head
- · Easy mounting with large tolerances possible Distance of sensor head to magnetic ring from 0.1-1.0 mm
- Tolerates lateral misalignment +1 mm
- Warning signal when magnetic field is too weak (LED)

#### **Technical data magnetic sensor LI20:**

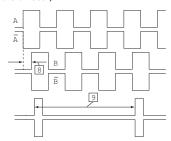
3					
Output circuit:	Push-Pull		RS422		
Supply voltage:	4.8-30 VDC		4.8-26 VDC		
Load/channel, max. cable length:	±20 mA, max. 3	30 m	120 Ohm, RS422 standard		
Current consumption (without load):	typ. 25 mA, max	x. 60 mA			
Short-circuit proof outputs 1):	yes		yes <sup>2)</sup>		
Min. Pulse interval:	1 μs (edge interval) corresp. to 4 μs/period (see signal figures at right)				
Output signal:	A	$A, \overline{A}, B, \overline{B}, I, \overline{I}$			
Reference signal:	Ir	ndex periodical			
Accuracy:					
System accuracy:	ty	yp. ±0.3° with sh	with shaft tolerance g6		
Repeat accuracy:	±	±1 increment			
Admissible alignment tolerance:					
Gap sensor / magnetic ring:	0	0.1-1.0 mm (recommended 0.4 mm)			
Offset:	m	max. ±1 mm			
Tilting:	m	max. 3°			
Torsion:	max. 3°				
Environmental conditions:					
Working temperature:	-4	-4 to +176°F (-20 to +80°C)			
Vibration resistance:	30 g (300 m/s²), 10-2000 l		0-2000 Hz		
Shock resistance:	5	500 g (5000 m/s <sup>2</sup> ), 1 ms			
Protection class:	IF	IP67 according to DIN 60 529 (housing)			
Humidity:	1	100%, condensation possible			
Housing:	Z	Zinc die-cast			
General data:					
Cable:		2 m, PUR 8 x 0.14 may be used in fle	mm2, shielded, exing cable installations		
Status-LED:	n	magnetic field too	ex; Red: Error, revs too high or o weak (for 0 and T8.LI20.XXXX.X050)		

**Technical data magnetic ring RI20:** 

Pole gap:	2 mm from pole to pole
Temperature ranges:	Working temperature: -4 to +185°F (-20 to +80°C) Storage temperature: -4 to +185°F (-20 to +80°C)
Mounting:	Screwed on shaft
System accuracy:	typ. +0.3° (at 77°F (25°C)), Sensor/Magnetic ring distance 0.5 mm and drive shaft tolerance g6 in accordance with ISO 286-2

#### Signal figures

with rotation of the magnetic ring in the CW-direction (see "permissible mounting tolerances")



- 8 Min. Pulse interval: pay attention to the instructions in the technical data
- 9 periodic index signal (every 2mm) the logical assignment A, B and I-signal can change

E56 B1027

RoHS compliant acc. to EU guideline 2002/95/EG

<sup>1)</sup> With supply voltage correctly applied

<sup>&</sup>quot;with supply voltage correctly applied "2" A max. of one channel only may be short-circuited: (when +V = 5 V, a short-circuit to another channel, 0 V, or +V is permissible.) (When +V = 5-30 V, a short-circuit to another channel or to 0 V is permissible.)

# Magnetic rings RI20/LI20

#### Part number key: LI20

## T8.LI20.11X1.2XXX

/lodel		Code*	
model	_	005 016	* Annotations see table "selection guide", col 3
Design		020	
= standard		050	
Pulse interval		Reference signal 2 = index periodic	
1 = standard		·	
Voltage supply and output circuit		Type of connection  1 = cable (PUR), 2 m	

1 = 4.8-26 VDC, RS422

2 = 4.8-30 VDC, push-pull

### Part number key: RI20

## 8.RI20.XXX.XXXX.111

•		
Model	Bore diameter	
Outer diameter	0800 = 8 mm 0952 = 9.525 mm (3 / 8") 1000 = 10 mm	1800 = 18 mm 2000 = 20 mm 2500 = 25 mm
031 = 31 mm 041 = 41.2 mm 045= 45 mm	1000 = 10 mm 1200 = 12 mm 1500 = 15 mm 1587 = 15,875 mm (5 / 8")	2540 = 25 mm (1") 3) 2540 = 25,4 mm (1") 3) 3000 = 30 mm 3)

Selection guide: magnetic sensor Li20/magnetic ring RI20

Pulses/ ppr	Part number for magnetic ring RI20	Part number for magnetic sensor LI20*	Max. rpm
250	8.RI20.031.XXXX.111	T8.LI20.11X1.2005	12,000
1000	8.RI20.031.XXXX.111	T8.LI20.11X1.2020	2,400
2500	8.RI20.031.XXXX.111	T8.LI20.11X1.2050	3,900
1024	8.RI20.041.XXXX.111	T8.LI20.11X1.2016	7,000
360	8.RI20.045.XXXX.111	T8.LI20.11X1.2005	12,000
3600	8.RI20.045.XXXX.111	T8.LI20.11X1.2050	2,700

<sup>\*</sup>At the listed rotational speed the min. pulse interval is 1  $\mu$ s, this corresponds to 250 kHz. For the maximum rotational speed range a counter with a count input frequency of not less then 250 kHz should be provided.

#### Pin assignment:

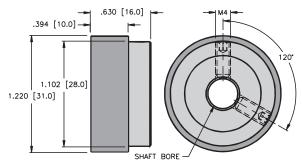
 $^{\scriptscriptstyle{(3)}}$  only possible for outer diameters 041 and 045

Signal:	0 V, GND	+V	Α	Ā	В	B	I	Ī
Color:	WH	BN	GN	YE	GY	PK	BU	RD

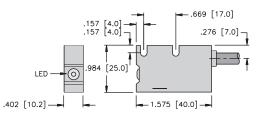
Shield is on the housing

## **Dimensions: RI20 magnetic ring**

### 8.RI20.031.XXXX.111, Ø 31 mm



## **Dimensions: Magnetic sensor LI20**



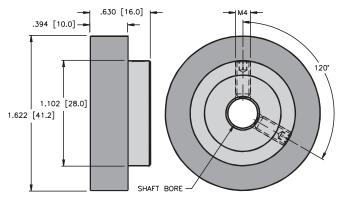
# **Rotary Position Technology**



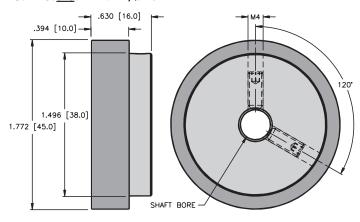
# Magnetic rings RI20/LI20

#### **Dimensions: RI20 magnetic ring**

### 8.RI20.041.XXXX.111, Ø 41.2 mm



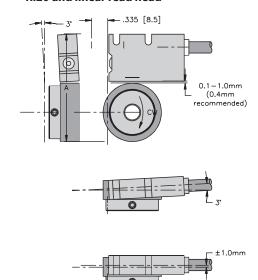
#### 8.RI20.045.XXXX.111, Ø 45 mm



Recommended tolerance of the drive shaft diameter: g6 in accordance with ISO 286-2  $\,$ 

#### Permissible mounting tolerances:

#### RI20 and linear read head



Part Number	Dimension A
8.RI20.031.XXXX.111	56.4 <sup>1)</sup>
8.RI20.041.XXXX.111	66.6 <sup>1)</sup>
8.RI20.045.XXXX.111	70.4 1)

1) Distance calculated with 0.4 mm between the sensor and magnetic ring

# Display type 572 for LI20



Counter series for demanding applications, with two individually scalable encoder inputs. HTL or TTL in each case A,  $\overline{A}$ , B,  $\overline{B}$  for count frequencies up to 1 MHz per channel. Operating modes can be selected for position or event counter, total counter, difference counter, cut-to-length display, diameter calculator, batch counter and more.

- Two separate freely scalable count inputs - HTL or TTL; also with inverted inputs
- Max. input frequency 1 MHz/ channel
- Four freely programmable fast solid-state outputs, each with 350 mA output current
- Step or tracking preset
- AC and DC supply voltage
- Can be used as a counter or position display with limit values
- Monitoring function, where two values are monitored or calculated with respect to each other
- Four fast programmable inputs with various functions such as reset, gate, display memory, reference input or switching between the display values.
- Optional scalable analog output 0/4-20 mA, +/-10 V or 0-10 V

- Two auxiliary power supplies for sensors: 5.2 VDC and 24 VDC
- Standard interface RS232

Part number key specification:
Position display, 6 digits, with 4 fast switch outputs and serial interface: 6.572.0116.
D05

**Position display, 6 digits,** with 4 fast switch outputs and serial interface and scalable analog output: 6.572.0116.D95

**Position display, 8 digits,** with 4 fast switch outputs and serial interface: 6.572.0118.

**Position display, 8 digits**, with 4 fast switch outputs and serial interface and scalable analog output: 6.572.0118.D95