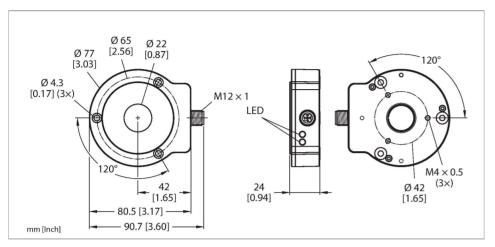


RI360P0-QR24M0-ELIU5X2-H1151 Contactless Encoder – Analog Premium Line





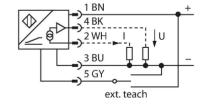
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Туре	RI360P0-QR24M0-ELIU5X2-H1151	
ID	1590908	
Measuring principle	Inductive	
General data		
Max. rotational speed	12,000 rpm	
	Determined with standardized construction, with a steel shaft Ø 20 mm, L = 50 mm and reducer Ø 20 mm	
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle	
Resolution	16 bit	
Measuring range	0360 °	
Nominal distance	1.5 mm	
Repeat accuracy	≤ 0.01 % of full scale	
Linearity deviation	≤ 0.05 % f.s.	
Temperature drift	≤ ± 0.004 %/K	
Output type	Absolute singleturn	
Resolution singleturn	16 Bit	
Electrical data		
Operating voltage U _B	1530 VDC	
Ripple U _{ss}	≤ 10 % U _{Bmax}	
Isolation test voltage	0.5 kV	
Short-circuit protection	yes	
Wire break/reverse polarity protection	yes/yes (voltage supply)	

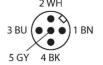


Features

- Compact and robust housing
- ■Versatile mounting options
- ■Status displayed via LED
- Measuring range indicated via LED
- Immune to electromagnetic interference
- Measuring range programmable via Easy Teach
- ■Output signal programmable via Easy Teach
- Resolution, 16-bit
- ■15...30 VDC
- ■0...10 V and 4...20 mA
- Male M12 x 1, 5-pin

Wiring diagram





Functional principle

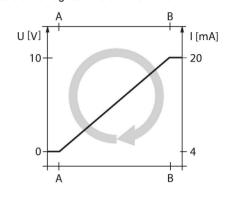
The measuring principle of inductive angle sensors is based on oscillation circuit coupling



Technical data

Output function	5-pin, Analog output	
Voltage output	010 V	
Current output	420 mA	
Diagnostic	Positioning element not within detection range: Output signal 24 mA or 11 V	
Load resistance voltage output	≥ 4.7 kΩ	
Load resistance current output	≤ 0.4 kΩ	
Sample rate	5000 Hz	
Current consumption	< 50 mA	
Mechanical data		
Design	QR24	
Dimensions	81 x 78 x 24 mm	
Flange type	Flange without mounting element	
Shaft Type	Hollow shaft	
Shaft diameter D (mm)	6 6.35 9.525 10 12 12.7 14 15.875	
	20	
Housing material	20 Metal/plastic, ZnAlCu1/PBT-GF30-V0	
Housing material Electrical connection		
	Metal/plastic, ZnAlCu1/PBT-GF30-V0	
Electrical connection	Metal/plastic, ZnAlCu1/PBT-GF30-V0	
Electrical connection Environmental conditions	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1	
Electrical connection Environmental conditions	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C	
Electrical connection Environmental conditions Ambient temperature	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C	
Electrical connection Environmental conditions Ambient temperature Vibration resistance	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm)	
Electrical connection Environmental conditions Ambient temperature Vibration resistance Vibration resistance (EN 60068-2-6)	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm) 20 g; 103000 Hz; 50 cycles; 3 axes	
Electrical connection Environmental conditions Ambient temperature Vibration resistance Vibration resistance (EN 60068-2-6) Shock resistance (EN 60068-2-27) Continuous shock resistance (EN	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm) 20 g; 103000 Hz; 50 cycles; 3 axes 100 g; 11 ms ½ sine; 3 × each; 3 axes	
Electrical connection Environmental conditions Ambient temperature Vibration resistance Vibration resistance (EN 60068-2-6) Shock resistance (EN 60068-2-27) Continuous shock resistance (EN 60068-2-29)	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm) 20 g; 103000 Hz; 50 cycles; 3 axes 100 g; 11 ms ½ sine; 3 × each; 3 axes 40 g; 6 ms ½ sine; 4000 × each; 3 axes IP68	
Electrical connection Environmental conditions Ambient temperature Vibration resistance Vibration resistance (EN 60068-2-6) Shock resistance (EN 60068-2-27) Continuous shock resistance (EN 60068-2-29) Protection class	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm) 20 g; 103000 Hz; 50 cycles; 3 axes 100 g; 11 ms ½ sine; 3 × each; 3 axes 40 g; 6 ms ½ sine; 4000 × each; 3 axes IP68 IP69K 138 years acc. to SN 29500 (Ed. 99) 40	
Electrical connection Environmental conditions Ambient temperature Vibration resistance Vibration resistance (EN 60068-2-6) Shock resistance (EN 60068-2-27) Continuous shock resistance (EN 60068-2-29) Protection class MTTF	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm) 20 g; 103000 Hz; 50 cycles; 3 axes 100 g; 11 ms ½ sine; 3 × each; 3 axes 40 g; 6 ms ½ sine; 4000 × each; 3 axes IP68 IP69K 138 years acc. to SN 29500 (Ed. 99) 40 °C	
Electrical connection Environmental conditions Ambient temperature Vibration resistance Vibration resistance (EN 60068-2-6) Shock resistance (EN 60068-2-27) Continuous shock resistance (EN 60068-2-29) Protection class MTTF Power-on indication	Metal/plastic, ZnAlCu1/PBT-GF30-V0 Connector, M12 × 1 -25+85 °C Acc. to UL approval to +70 °C 55 Hz (1 mm) 20 g; 103000 Hz; 50 cycles; 3 axes 100 g; 11 ms ½ sine; 3 × each; 3 axes 40 g; 6 ms ½ sine; 4000 × each; 3 axes IP68 IP69K 138 years acc. to SN 29500 (Ed. 99) 40 °C LED, Green	

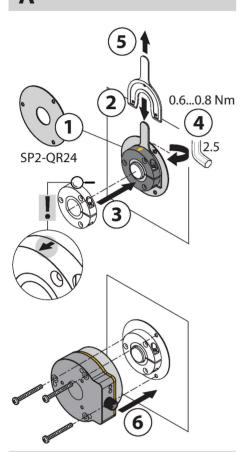
between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. The rugged sensors are wear and maintenance-free, thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures a high immunity to electromagnetic DC and AC fields.

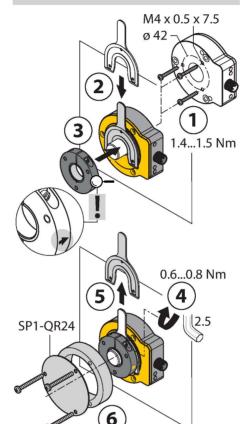


Mounting instructions

Mounting instructions/Description

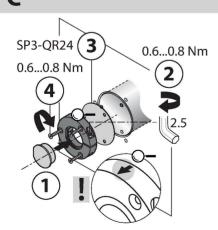
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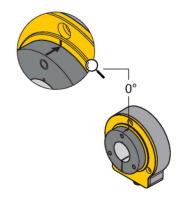




B

Default: 0°





The extensive range of mounting accessories enables easy adaptation to many different shaft diameters. Due to the measuring principle, which is based on the functional principle of an RLC coupling, the encoder is immune to magnetized ferrous chips and other interferences. As a result, there are few possible causes of error during mounting. The adjacent figures show the simple installation of the two separate units: the sensor element and the positioning element: Mounting option A:

First, connect the positioning element to the rotatable shaft using the bracket. Then place the encoder with the aluminum ring above the rotating part in such a way that you get a closed and protected unit.

Mounting option B:

Slide the encoder backward onto the shaft and fasten it to the machine. Then fasten the positioning element to the shaft using the bracket.

Mounting option C:

If the positioning element is screwed onto a rotating machine part rather than being put on a shaft, you must first insert the dummy plug RA8-QR24. Then tighten the bracket. Next. mount the encoder via the three bores.

Due to the separate installation of positioning element and sensor, no electrical currents or harmful mechanical forces are transmitted to the sensor via the shaft. The encoder also offers a high degree of protection throughout its service life and stays permanently sealed. During commissioning, the accessories included in the delivery help to mount the encoder and the positioning element at an optimal distance from each other. In addition, LEDs indicate the status. Optionally, you can use the shield plates included in the accessories to increase the permitted distance between the positioning element and the sensor.

Status display via LED Green:
Sensor is being supplied properly Yellow:
Positioning element is within the measuring range, low signal quality (e.g. distance too great)
Yellow flashing:
Positioning element is outside the detection range
Off:
Positioning element is within the measuring range Due to the separate installation of positioning

Individual Parameterization (Tea	ching with Positioning Element)
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Bridge between teach input Pin 5 (GY)	Gnd Pin 3 (BU)	Ub Pin1 (BN)	LED
2 s	Start value	End value	Status LED flashes then turns steady after 2 s
10 s	CCW rotation, then return to last preset value	CW rotation, then return to last preset value	After 10 s status LED flashes fast for 2 s
15 s	-	Factory setting (360°, CW)	after 15 s power and status LED alternate

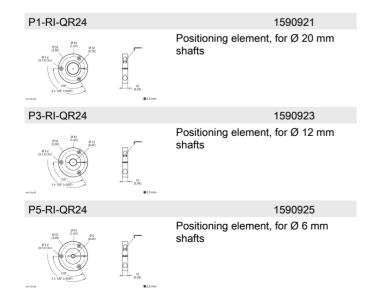
To avoid unintended teaching, keep pin 5 potential-free.

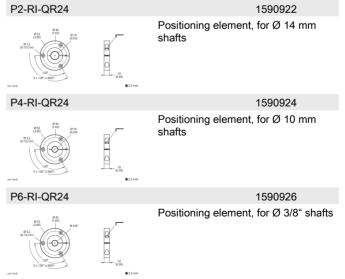
Preset Parameterization (Teaching without Positioning Element)

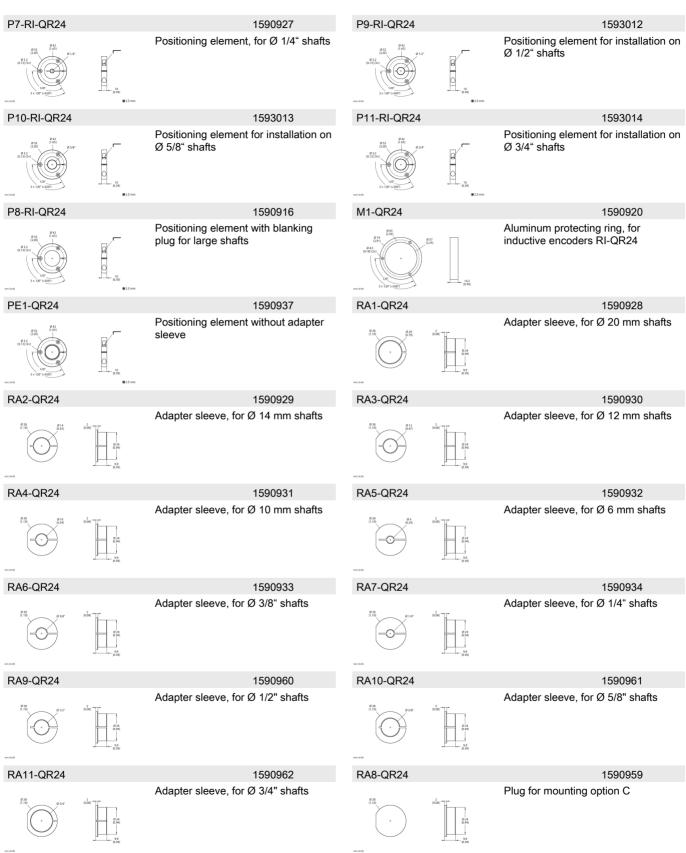
Bridge pin between teach input Pin 5 (GY)	Gnd Pin 3 (BU)	Ub Pin 1 (BN)	LED
2 s	Activate selection mode for output signal (for 10 s)	Activate preset mode (for 10 s)	Status LED steady, flashes after 2 s
10 s	CCW rotation direction	CW rotation direction	After 10 s status LED flashes fast for 2 s
15 s		Factory setting (360°, CW)	After 15 s power and status LED flash equally fast
Output configuration	Gnd Pin 3 (BU)		Status LED
I out: 420 mA	Press once		1 x flashing
I out: 020 mA	Press twice		2 x flashing
Uout: 010 V	Press three times		3 x flashing
Uout: 05 V	Press four times		4 x flashing
Uout: 0.5 V / 4.5 V	Press five times		5 x flashing
Preset mode / Angular		Ub Pin 1 (BN)	Status LED
range			
45°		Press once	1 x flashing
60°		Press twice	2 x flashing
90°		Press three times	3 x flashing
180°		Press four times	4 x flashing
270°		Press five times	5 x flashing

To avoid unintended teaching, keep pin 5 potential-free.

Accessories







RI360P0-QR24M0-ELIU5X2-H1151| 02/21/2025 14-54 | technical changes reserved



