

Your Global Automation Partner

TURCK

How to Select the Right Positioning Sensor Solution

White Paper - W1010

These non-contact sensors incorporate an advanced microprocessor circuit and precisely manufactured printed emitter and receiver coil systems. During operation, the emitter coils are activated with a high frequency AC field and produce an inductive RLC circuit with the positioning element. The element is inductively coupled with the receiver coils, which are arranged so different voltages are induced in the coils, depending on the position of the actuator. The voltages serve as a measure for the sensor signal. These sensors deliver maximum measuring spans, with minimal blind zone and high resistance to EMI/RFI noise interference.

With the non-contact linear positioning sensor featuring an innovative three-coil design, the excitation coil is surrounded by two sensor coils. **Figure 1** (page 2) illustrates a simplified sensor coil design for a non-contact linear positioning element. As shown in **Figure 1**, its coupling

factor to the resonator is relatively constant, which causes the positioning element to be continuously powered when it is within the measurement range. The Cosine and Sine coils are patterned so that their coupling factors to the resonator k_{COS} and k_{SIN} vary sinusoidally along the measurement range. Since the sensor coils are balanced, with sections wound in opposite directions, any inductive interference is effectively cancelled out.

Upon activation, a high frequency AC field (EX waveform) is emitted from the excitation coil. When the excitation coil is shut off, the Sine and Cosine tracks will pick up the resulting inductive field (echo) created in the positioning element. An internal microprocessor analyzes the signals and produces an output. The outputs available for this coil design are typically voltage (0 to 10V) and current (4 to 20 mA). This is demonstrated in **Figure 2**.

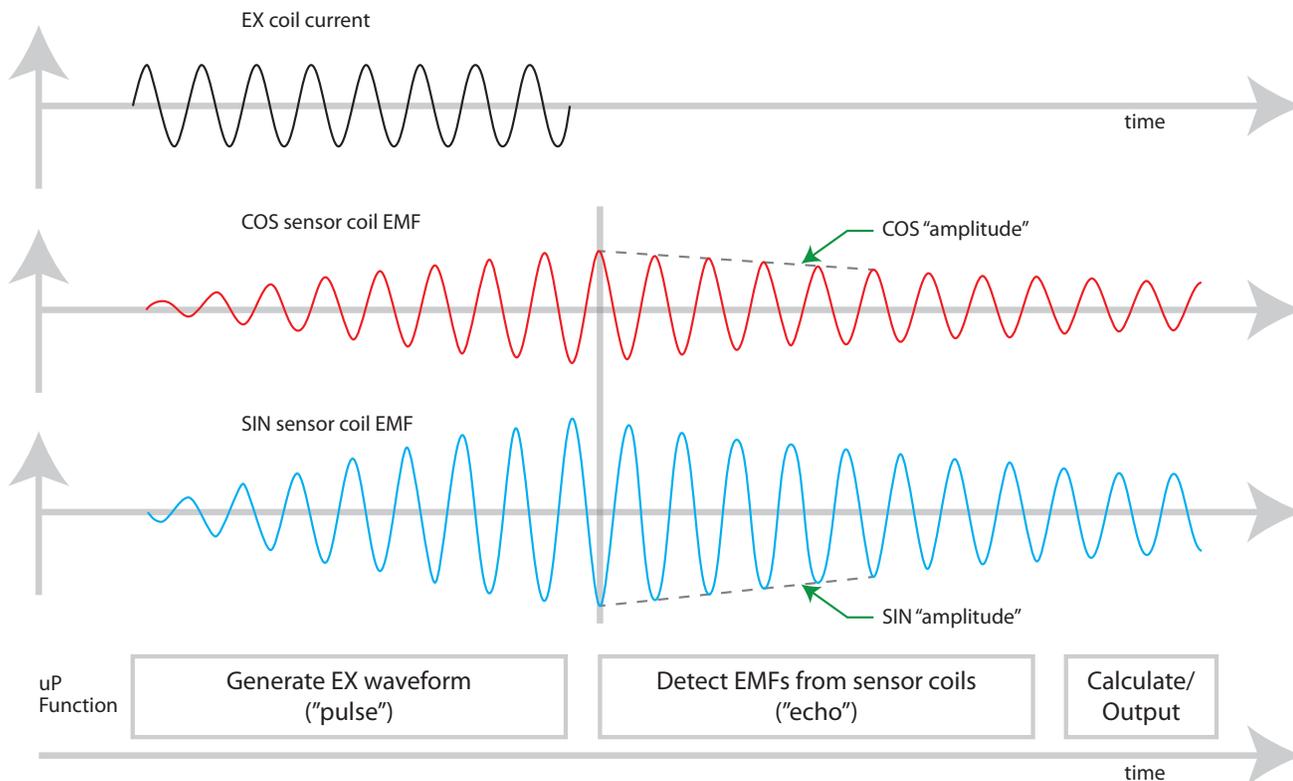


Figure 2

Along with the three-coil design, inductive sensors are also offered in a dual Sine/Cosine coil system that uses the same principal of operation as the three-coil design. This system features course coils and fine coils for the Sine/ Cosine tracks, delivering fast and precise measurement over longer distances with the course tracks enabling the microprocessor to locate the positioning element faster and then the fine coils determine its precise position. Additionally, the feedback signal is available in either analog (12 bit), analog with I/O Link (16 bit) or SSI (25 bit). All position calculations are performed using specially designed microprocessor circuitry.

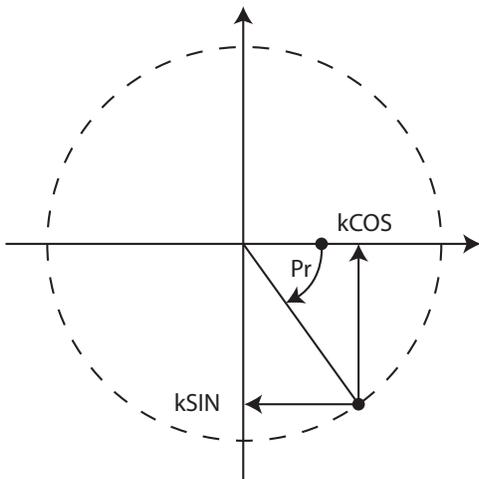


Figure 3

For rotary applications, non-contact rotary sensors use the same coil principal, but the coils are arranged in a circle formation and are patterned to produce a sine/cosine variation of the couple factor when the position changes (Figure 3). To further enhance accuracy and performance, rotary inductive sensors feature electronics that can compensate for misalignment between the positioning element and the sensor. The microprocessor can analyze the sine and cosine signals and compare the outputs against the expected position and compensate for lateral misalignments of up to 1.5 mm.

PERFORMANCE COMPARISON OF SENSOR TECHNOLOGIES

When selecting the ideal position sensor, it is critical that users are able to identify the individual strengths and limitations associated with each potential solution. The tables below provide a snapshot comparison between inductive sensors based on the RLC operating principal and other available technologies in the marketplace, including potentiometer, magnetostrictive, optical encoders and variable differential transformers.

Potentiometers

Featuring a simplistic operating principle, potentiometers remain a common solution for displacement measurement. As a contact solution, potentiometers require that contact must be made along a precise path with uniform force for accurate results. This causes friction that can result in wear and tear and ultimately impacts productivity. Additionally, since these sensors are not engineered to withstand harsh environments, they are prone to failure from wear and moisture ingress.

Magnetostrictive

Another commonly used sensor solution for linear positioning is magnetostrictive sensors. Containing ferromagnetic materials, they are used to measure the position of a moving magnet. To detect an objects' position, a strain pulse is applied to a magnetostrictive wire that runs the entire length of the probe. When the strain pulse encounters a magnetic field produced by the slide or floating magnet assembly, a current pulse is produced. With this technology, the linear positioning is measured by the time difference between the pulses in relationship to the preprogrammed "zero" and "span" to be detected. Due to their ferromagnetic makeup, magnetostrictive sensors can be problematic in applications containing magnetic fields, as this will

cause interference with the sensors, leading to performance errors and measurement inaccuracies. Further, any interruption costs users additional expenses from lost production and downtime for troubleshooting and equipment replacements.

Optical Encoders

Optical encoders offer fast response times and simple output interface. However, they can be expensive to build into products, particularly when high resolution is required, since they require their own bearings to avoid any misalignment. Many encoders also lack inherent durability against the ingress of dirt, dust or moisture, making them unsuitable for multiple environments.

Hall Effect Encoders

Hall Effect encoders integrate Hall Effect sensors and interpolation electronics on a single chip. Used with a rotating magnet, they deliver a precise measurement of angular position, but they are also extremely sensitive to misalignment, which typically requires them to be manufactured as a packaged device with bearings to

compensate. Linear sensing is also possible with a linear magnetic track but misalignment is also a large factor in output accuracy and reliability.

Linear Variable Differential Transformer

Linear variable differential transformers (LVDTs), and their rotary counterpart rotary variable differential transformers (RVDTs) are electromechanical transducers that provide a variable alternating current output used to measure either linear or rotary displacement. While they offer a rugged solution for demanding applications, they are expensive to manufacture and do not offer some of the more sophisticated features found in the inductive sensors, such as their ability to compensate for misalignment or accommodating multi-axis sensing.

Inductive Sensors with RLC Operation

Since inductive sensors utilizing the RLC operating principle have their sensing coils imprinted on a PCB, they are much simpler and easier to manufacture and offer improved precision. This extra design freedom available

Absolute Linear Position Sensor Comparison

| | Potentiometer | Magnetostrictive | Optical Encoder | LVDT | RLC |
|-----------------------------------|---------------|------------------|-----------------|------|-----|
| Wear free? | No | Yes | Yes | Yes | Yes |
| Works in dust & dirt w/out seals? | No | No | No | Yes | Yes |
| Tolerant to misalignment? | No | Yes | No | No | Yes |
| Operates at big gaps? | No | No | No | No | Yes |
| Short inactive zones? | Yes | No | Yes | No | Yes |

Absolute Rotary Position Sensor Comparison

| | Potentiometer | Hall Effect Encoder | Optical Encoder | RVDT | RLC |
|-----------------------------------|---------------|---------------------|-----------------|------|-----|
| Wear free? | No | Yes | Yes | Yes | Yes |
| Works in dust & dirt w/out seals? | No | Yes | No | Yes | Yes |
| Tolerant to misalignment? | No | No | No | No | Yes |
| Operates at big gaps? | No | No | No | No | Yes |

from PCB coils means that the sensors are engineered to be highly tolerant of misalignment and rarely require additional bearings.

Inductive sensors equipped with fully sealed housing provide dependable performance by preventing moisture and dust ingress and avoiding sensor malfunction. Their non-contact design allows these sensors to accommodate applications with constant motion without resulting in costly wear, while their non-magnetic properties eliminate the risk of interference from magnetic fields that impact results.

These sensors were developed with small blind zones relative to the measuring track giving the designer the ability to use a sensor in a confined area (**Figure 4**). Plus, offered with numerous features and performance capabilities, these sensors provide superior flexibility—allowing them to accommodate a wide range of applications.

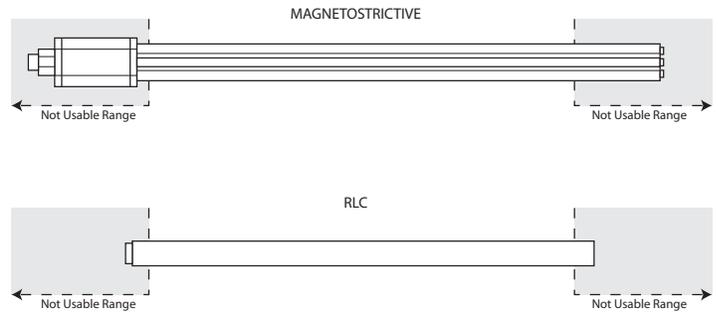


Figure 4

CONCLUSION

As industries continue to adopt newer machine designs that complement production and efficiency strategies, selecting sensing components that promote these initiatives is key. Therefore, utilizing inductive sensors that deliver more accurate results, minimize downtime and increase flexibility can ensure continued productivity, profitability and product quality.

TURCK

28 subsidiaries and over
60 representations worldwide!

Printed in USA

©2017 by Turck Inc. All rights reserved. No part of the
publication may be reproduced without written permission.

W1010 B 09/17

www.turck.com